
Robotc 4 X Keygen 98

```
1  #pragma config(StandardModel, "POE + CIM Testbed")
2  /**!!Code automatically generated by 'ROBOTC' configuration wizard      !**//
3
4  //Michael Wooten    1/6/16    POE    Activity 3.1.2 Part 3
5
6  task main()
7  {
8  startMotor(rightMotor, 63); //Turn the rightMotor on forward at half speed
9  wait(5); //for 5 seconds
10 stopMotor(rightMotor); //then stop
11 startMotor(leftMotor, -95); //Turn the leftMotor on in reverse at three-fourths speed
12 wait(2.5); //for 2.5 seconds
13 stopMotor(leftMotor); //then stop
14 forward(127); //Turn both motors on at full power, and spinning in the same direction
15 wait(7.25); // for 7.25 seconds
16 stop(); //then stop
17
18
19 }
20
```

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